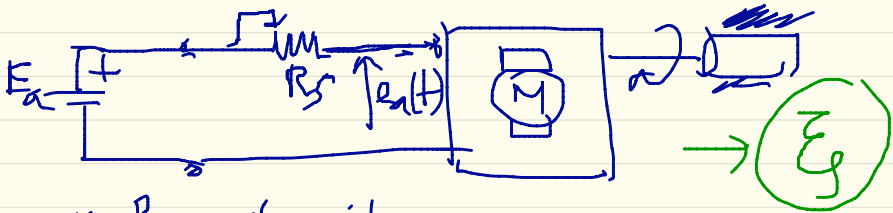
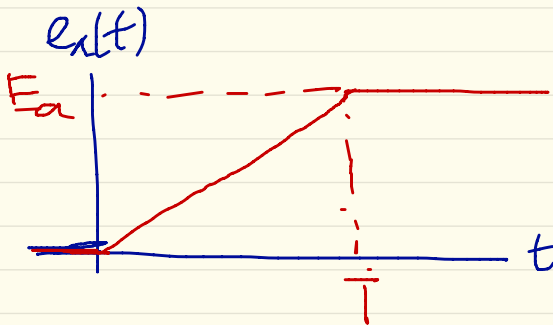
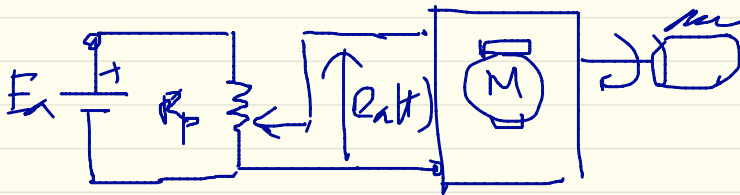


* open-loop Control (START & STOP)

* R_a - series:



* R_a - shunt



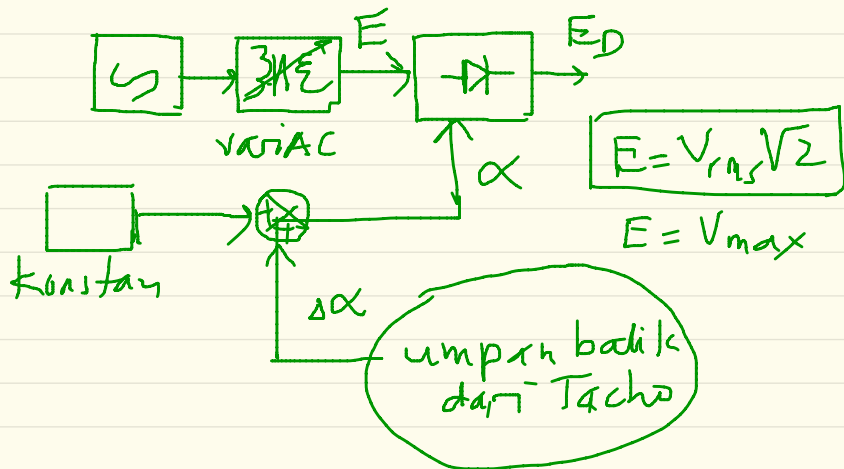
Tugas 3 : Mengimplementasikan
Open-loop Control di atas
pada model motor anda
masing-masing (ubah ω_g T)

09/4/12

1

* Closed-loop Control

- * Keadaan normal (semua berubah "NOMINAL")
- * Gangguan beban $\uparrow$
- * Pengendalian untuk putaran tetap



Penyearah Jembatan 1 ϕ :

$$E_D = \frac{E}{\pi} [1 + \cos \alpha]$$
$$0 \leq \alpha \leq \pi$$