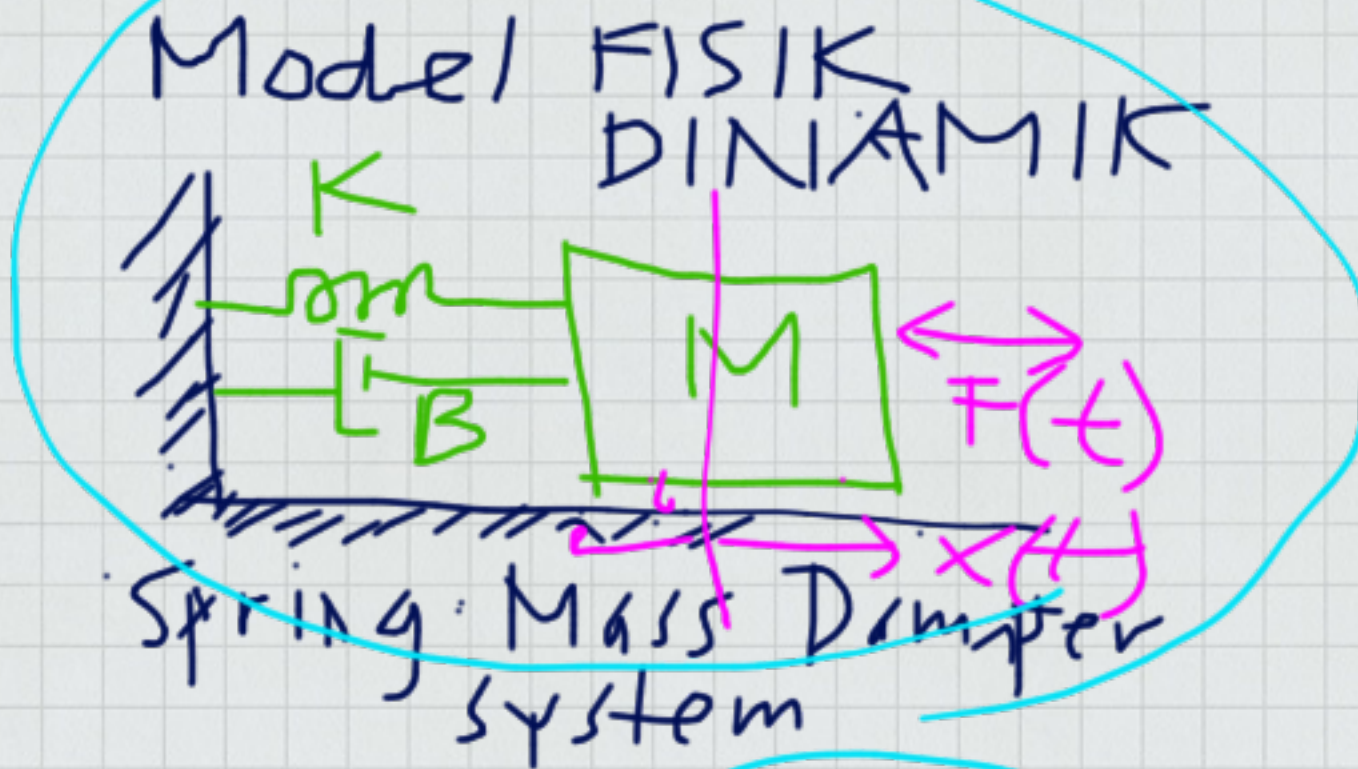
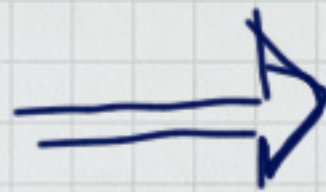
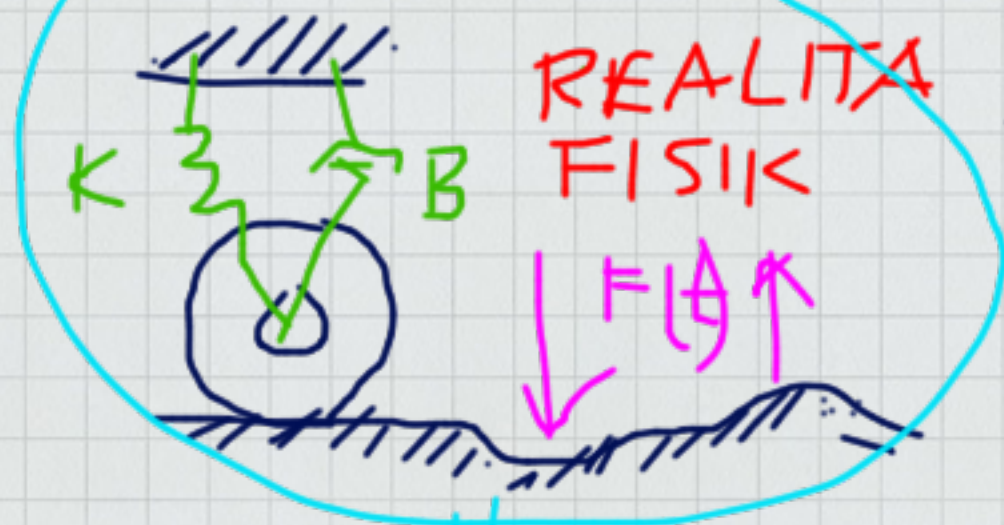


Sistem Suspensi Kendaraan Bermotor



Model MATEMATIK DINAMIK

* Pers. Differential.

HK. NEWTON

$$F(t) = M \frac{d^2 x(t)}{dt^2} + B \frac{dx(t)}{dt} + Kx(t)$$

* Nisbah Alih: $\frac{X(s)}{F(s)} = G(s)$

* Ruang Keadaan

* BAGIAN KOTAK

Simulasi ANALOG

Rangkaian ELEKTRONIKA

Model FISIK DINAMIK