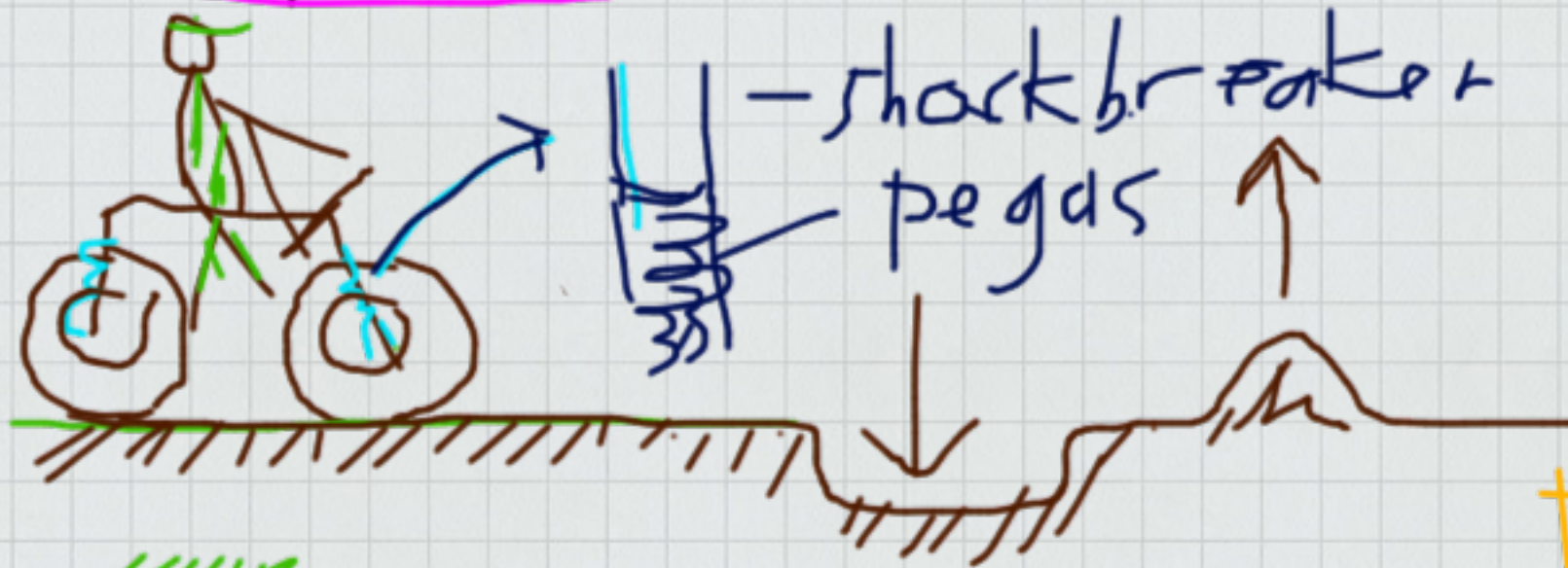
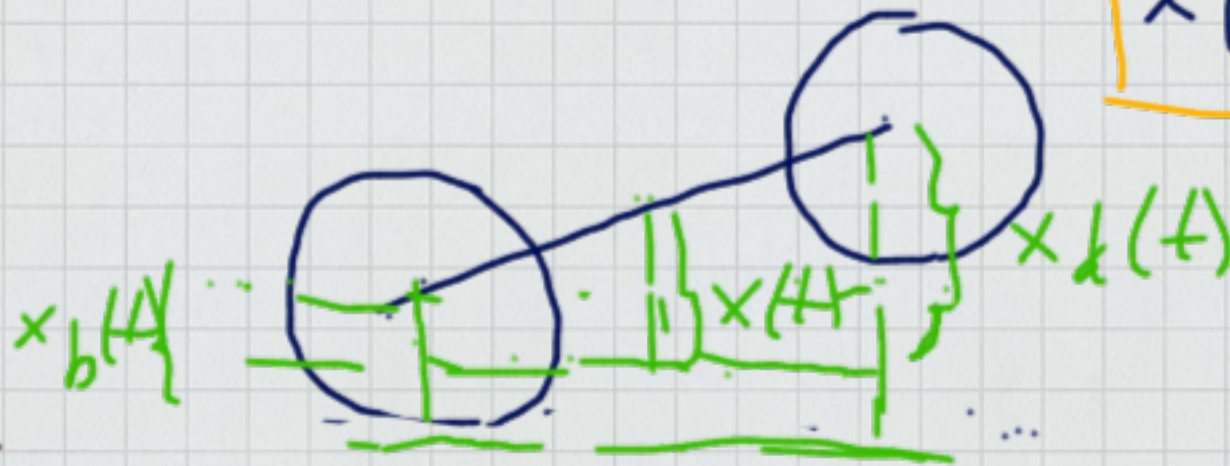
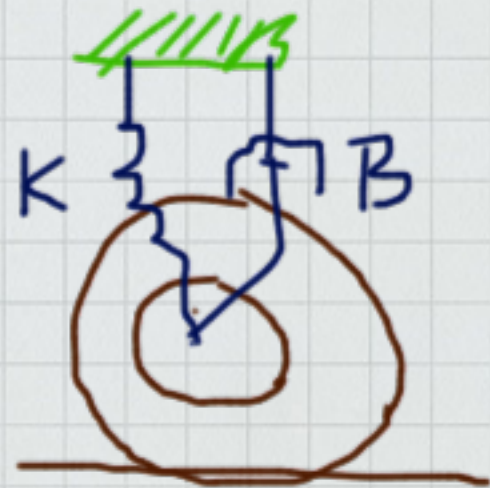


* PROJECT 2 : Sistem Suspensi Sepeda Motor



guncangan
pengendalian

$$x(t) = \frac{1}{2}(x_d(t) + x_b(t))$$



belak.
guncangan kan
roda depan

