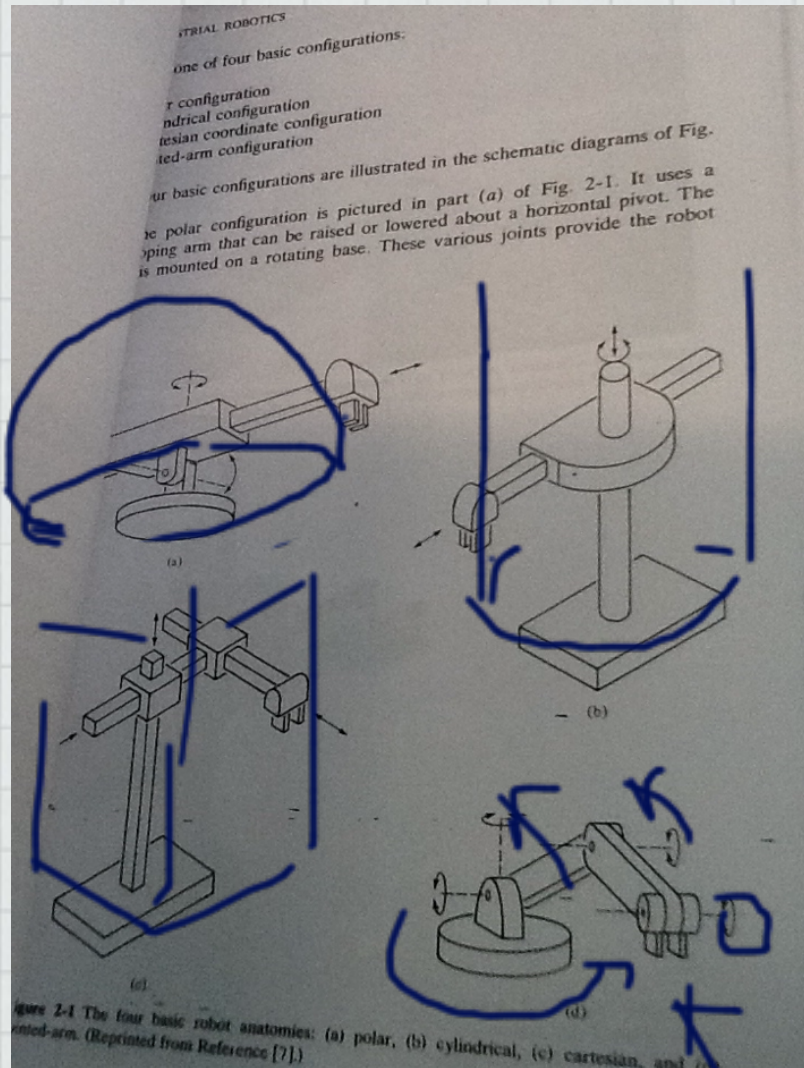


* ANATOMI ROBOT



Konfigurasi Robot:

- * POLAR
- * SILINDRIS
- * Kartesias
- * Persendian

Pola gerak → derajat
hal 2g ← "R" kebebasan
Fig 2-9
flexible
rotating 4 atau 6

"T" twisting

"L" linear
"V" revolusi