

$$\angle = \tan^{-1} \frac{y}{x+l_1} = 12,43$$

$$\frac{y_p}{x_p} = \tan(\theta_1 - \alpha) = \tan(17,57) = 0,3166 \rightarrow y_p = 0,3166 x_p$$

$$x_p^2 + (0,3166 x_p)^2 = 1,7257$$

$$1,3166 x_p^2 = 1,7257 \rightarrow x_p = \sqrt{\frac{1,7257}{1,3166}} = \underline{1,145}$$

$$y_p = 0,3166 \times 1,145 = 0,3625$$

Misalnya lengan robot diputar shg mencapai $R(-1, 0, 6)$
Ditanyakan θ_1, θ_2

