

* Tanggapan dan Kestabilan ←

Pers. Keadaan : $\dot{x} = Ax + Bu$

→ pers. differensial:

$$\frac{dx(t)}{dt} = Ax(t) + Bu(t)$$

diperoleh:

→ $x(t)$ = solusi pers. differensial
jika diketahui $x(0) = X_0$

Kasus

$u(t) = 0$ → solusi "khusus" $x(t)$

$u(t) \neq 0$ → solusi $x(t)$ → TANGGAPAN
atau RESPONSE thd $u(t)$

Skalar

$$\frac{dx(t)}{dt} = ax(t)$$
$$x(0) = X_0$$

a = skalar
 $x(t)$ = iparantungsh