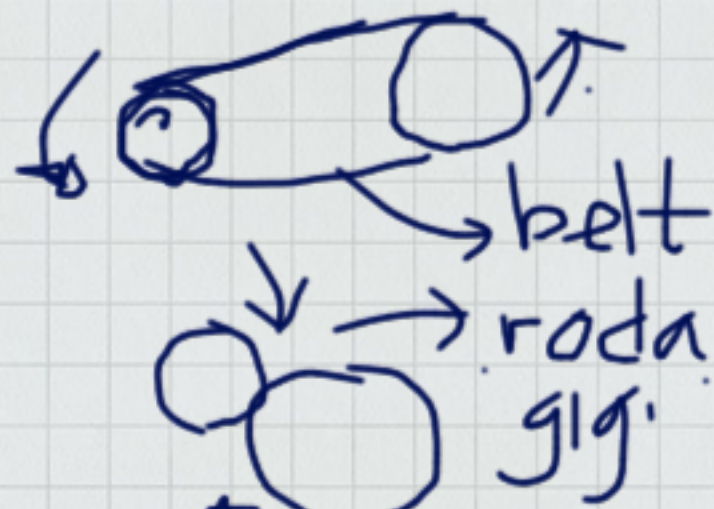


Model Fisik

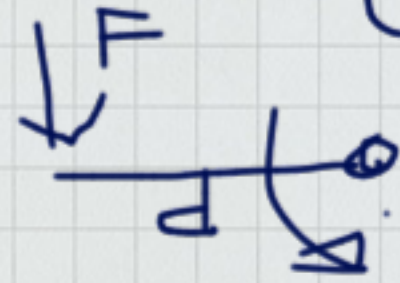


$J = \text{Inersia}$

B
(friksi)



penghasil Torsi
(Torque)



$$T = F \cdot d$$

$F = \text{gaya (N)}$

$d = \text{jarak (m)}$

$T = \text{torsi (N.m)}$

Motor = penghasil
torsi dari Arms

Motor DC

- * Terkendali Jangkar (Armature Controlled)

→ Medan Magnet tetap

- * Terkendali Medan (Field Controlled)

→ Medan Magnet berubah