

$$\underbrace{[sI - A]}_{[n \times n]} \underbrace{\dot{X}(s)}_{[n \times 1]} = \underbrace{B}_{[n \times 1]} \underbrace{U(s)}_{[1 \times 1]}$$

$$\underbrace{[sI - A]^{-1} [sI - A]}_I \dot{X}(s) = [sI - A]^{-1} B U(s)$$

$$\dot{X}(s) = [sI - A]^{-1} B U(s)$$

$$\mathcal{L} y(t) = \mathcal{L} x(t) + \mathcal{L} Du(t)$$

$$\underbrace{Y(s)}_{[1 \times 1]} = \underbrace{C}_{[1 \times n]} \underbrace{X(s)}_{[n \times 1]} + \underbrace{D}_{[1 \times 1]} U(s) = \underbrace{C}_{[1 \times n]} \underbrace{[sI - A]^{-1} B}_{n \times n} U(s) + \underbrace{D}_{[1 \times 1]} U(s)$$

$$Y(s) = \underbrace{[C [sI - A]^{-1} B + D]}_{[1 \times 1]} U(s)$$

$$\boxed{G(s) = \frac{Y(s)}{U(s)} = C [sI - A]^{-1} B + D} \quad [1 \times 1]$$