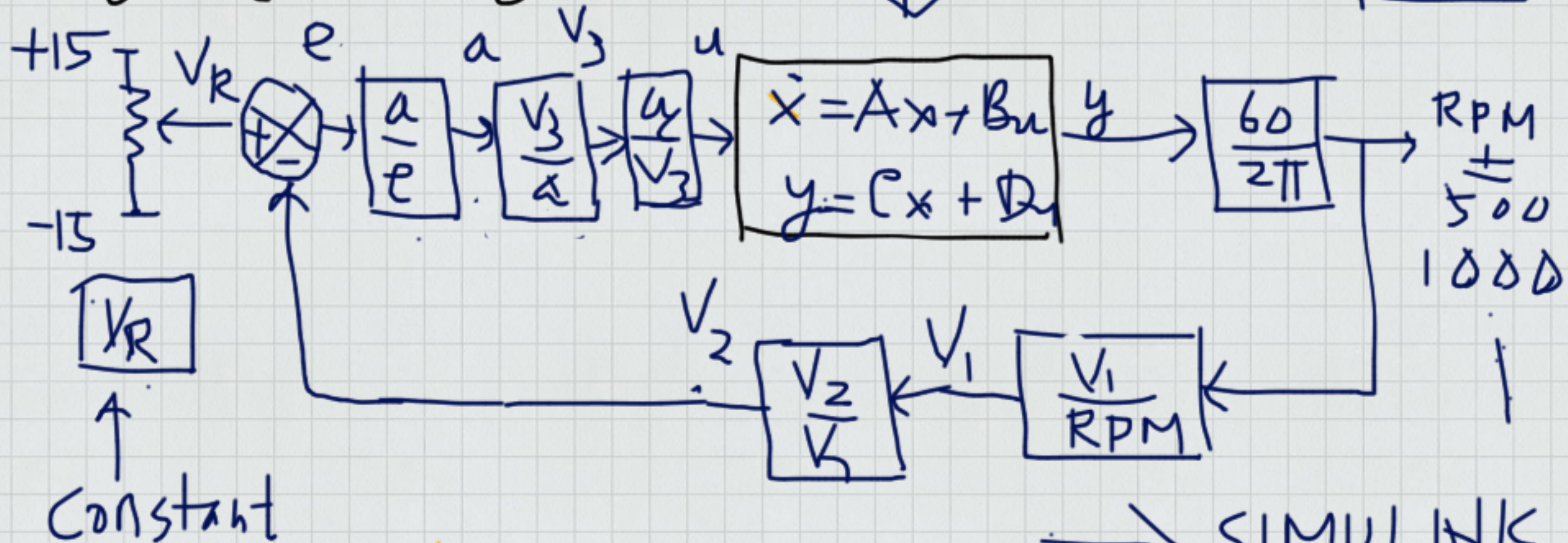


$$\dot{x} = \begin{bmatrix} -\frac{R_a}{L_a} & -\frac{K_b}{L_a} \\ \frac{K_m}{J} & -\frac{B}{J} \end{bmatrix} x + \begin{bmatrix} \frac{1}{L_a} \\ 0 \end{bmatrix} u$$

$$y = \begin{bmatrix} 0 & 1 \end{bmatrix} x$$

Display



⇒ FINAL = 8/12/2016

⇒ SIMULINK