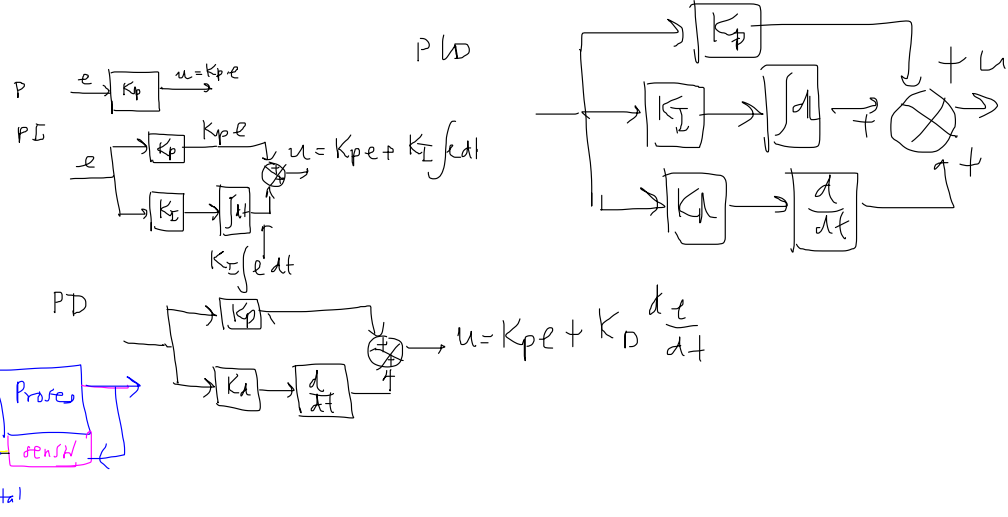
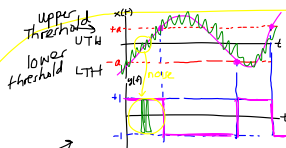
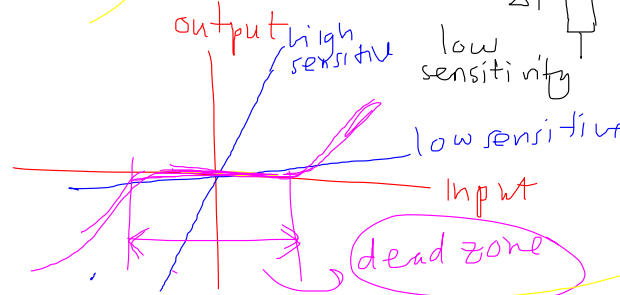
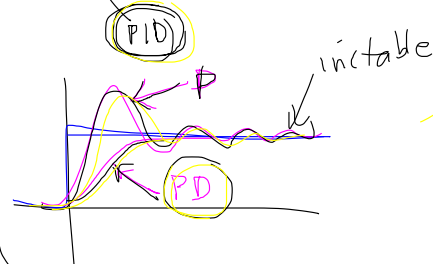
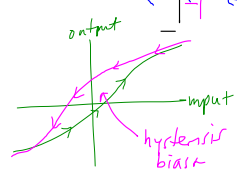


Diagram blok sistem kontrol:

x → [] → y
+ y (keluar)



$$\begin{pmatrix} y=+1, & x < +a \\ y=-1, & x > -a \end{pmatrix}$$



Sifat input-output :

- Hysteresis tegak
- Window Comparator
- Schmitt Trigger